

# CSE331 Introduction to Algorithms

## Lecture 15

### Minimum Spanning Trees

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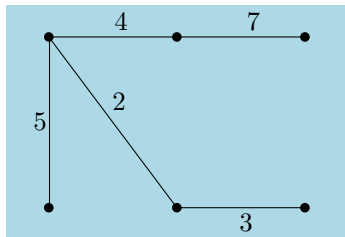
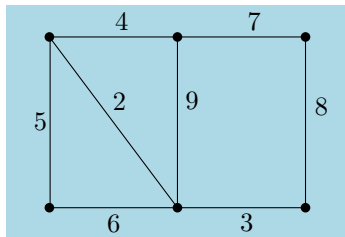
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# Introduction

- This lecture presents Prim's algorithm for computing a minimum spanning tree.
- It is a *greedy* algorithm.
- **Reference:** Chapter 23 of the textbook [Introduction to Algorithms](#) by Cormen, Leiserson, Rivest and Stein.
- I will not be following this textbook closely in this lecture.

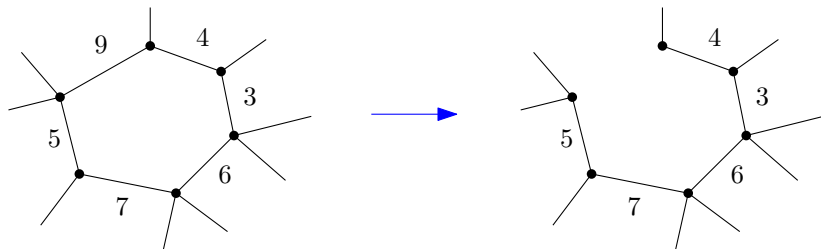
# Introduction

- Suppose that you want to build a communication network between locations  $v_1, v_2, \dots, v_n$ .
- Some pairs  $v_i, v_j$  can be connected by a direct link with cost  $w(v_i, v_j) > 0$ .
- The network should be connected, and as cheap as possible.
- Example:



# Introduction

- The network has to be a tree, because if it contained a cycle, we could remove the heaviest edge on this cycle, and the network would remain connected.



## Proposition

An undirected graph is a tree iff it is connected and has no cycle.

# Problem Statement

## Definition

A *spanning tree* of a graph  $G(V, E)$  is a tree whose edges are in  $E$ , and that connects all the vertices in  $V$ .

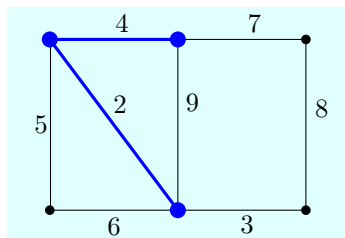
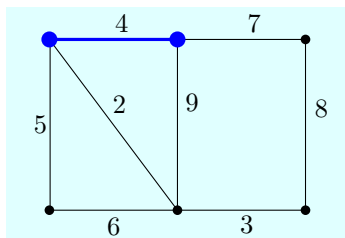
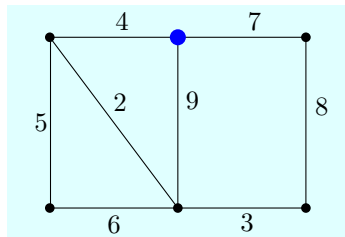
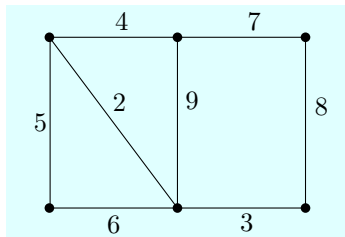
## Problem (Minimum Spanning Tree)

INPUT: a connected, undirected graph  $G(V, E)$  with weighted edges.

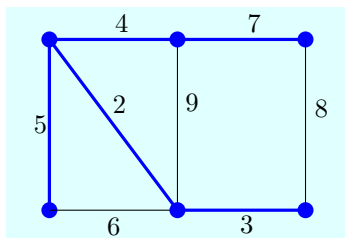
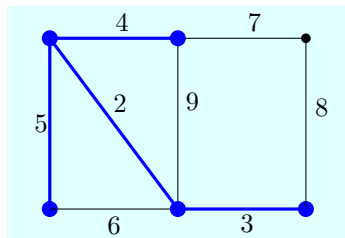
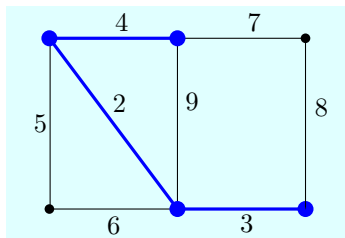
OUTPUT: a spanning tree  $T$  with minimum weight, called the *minimum spanning tree*.

- The brute force approach runs in exponential time as there is an exponential number of spanning trees.
- We will give a polynomial-time algorithm.

# Prim's Algorithm



# Prim's Algorithm



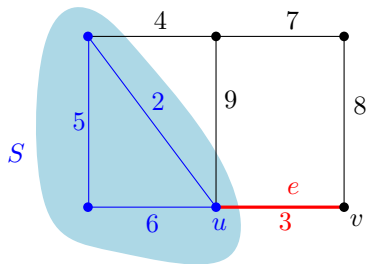


# Prim's Algorithm

## Pseudocode

```
1: procedure PRIM( $G(V, E)$ )
2:    $S \leftarrow \{r\}$  for some arbitrary  $r \in V$ 
3:    $F \leftarrow \emptyset$ 
4:   while  $S \neq V$  do
5:     Find edge  $(u, v) \in S \times (V \setminus S)$  with minimum weight
6:      $F \leftarrow F \cup \{(u, v)\}$ 
7:      $S \leftarrow S \cup \{v\}$ 
8:   return  $T = (V, F)$ 
```

# Proof of Correctness

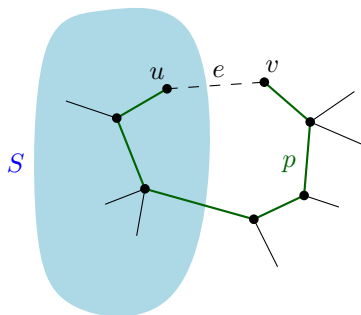


## Lemma

Assume that all edge weights are distinct. Let  $S \subset V$  be a subset of vertices such that  $S \neq \emptyset$  and  $S \neq V$ . Let  $e = (u, v)$  be the edge with smallest weight that starts at a vertex  $u \in S$  and ends at a vertex  $v \notin S$ . Then any MST contains  $e$ .

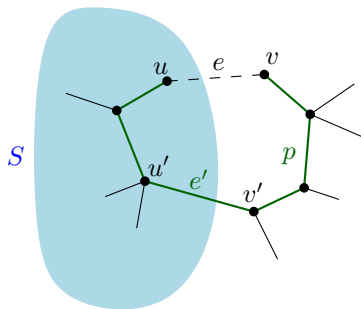
# Proof of the Lemma

- Proof by contradiction: Suppose that there is an MST  $T(V, F)$  such that  $e \notin F$ .
- There is a unique path  $p$  in  $T$  between the endpoints  $u \in S$  and  $v \notin S$  of  $e$ .



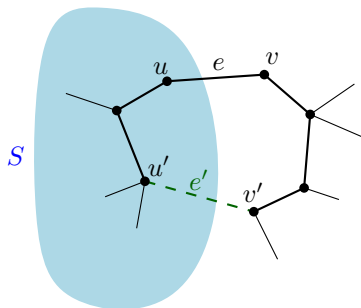
# Proof of the Lemma

- There must be an edge  $e' = (u', v')$  along  $p$  such that  $u' \in S$  and  $v' \notin S$ .



## Proof of the Lemma

- Consider  $T'(V, F')$  obtained from  $T$  by replacing  $e'$  with  $e$ . So  $F' = F \cup \{e\} \setminus e'$ .



- Then  $T'$  is a spanning tree with weight  $w(T) + w(e) - w(e') < w(T)$ , a contradiction.

# Proof of Correctness

- When all the weights are distinct, this lemma proves that Prim's algorithm picks an edge that lies in any MST at each step.
- At the end, we have  $n - 1$  edges that belong to any MST.
- So they form the unique MST, as any MST has exactly  $n - 1$  edges.

## Theorem

If all the weights are distinct, then the MST is unique, and Prim's algorithm computes it.

- If the weights are not distinct, then there can be several MSTs, and Prim's algorithm returns one of them. (Why?)

## Efficient Implementation

- Let  $n = |V|$  and  $m = |E|$  denote the number of vertices and edges of  $G$ .
- Then a naive implementation of Prim's algorithm (Slide 9) runs in time  $\Omega(nm)$ .
- We now show how to make it run in  $O(m \log n)$  time using a heap-based priority queue  $Q$ .
- At any time during the course of the algorithm,  $Q$  records for each  $v_j \in V \setminus S$  the lightest edge  $(p_j, v_j)$  where  $p_j \in S$ .
- The vertices in  $S$  are marked. (For instance, using a Boolean flag.)
- At Line 14, we update the key of an element of the queue. It can be done in  $O(\log n)$  time by deleting and reinserting it with the new key value. There is also a more direct way of implementing it.

# Prim's Algorithm: Detailed Pseudocode

```
1: procedure PRIM2( $G(V, E)$ )
2:    $Q \leftarrow$  empty priority queue
3:    $p[1, \dots, n] \leftarrow$  array of vertices
4:    $F \leftarrow$  empty list of edges
5:   for  $i = 1, n$  do
6:     Insert  $v_i$  into  $Q$  with  $\text{key}(v_i) = \infty$ 
7:   while  $Q \neq \emptyset$  do
8:      $v_i \leftarrow$  extract-min( $Q$ ) ▷ new vertex in  $S$ 
9:     Mark  $v_i$ 
10:    if  $\text{key}(v_i) \neq \infty$  then
11:       $F \leftarrow F \cup \{(p[i], v_i)\}$ 
12:    for each unmarked node  $v_j$  adjacent to  $v_i$  do
13:      if  $w(v_i, v_j) < \text{key}(v_j)$  then
14:        CHANGEKEY( $Q, v_j, w(v_i, v_j)$ )
15:         $p[j] \leftarrow v_i$ 
16:  return  $T = (V, F)$ 
```



# Prim's Algorithm

- We assume that  $m \geq n - 1$  as otherwise  $G$  is disconnected, and hence there is no MST. We also assume that  $n \geq 2$  as otherwise the problem is trivial.

## Theorem

Prim's algorithm, as implemented in Slide 16, runs in  $O(m \log n)$  time.

## Proof.

Each queue operation takes  $O(\log n)$  time. So, not counting the inner **for** loop, the algorithm runs in  $O(n \log n)$  time.

The inner **for** loop is iterated once for every  $v_i$  and every  $v_j$  adjacent to  $v_i$ . In other words, it is iterated twice for each edge  $(v_i, v_j)$ . Each iteration takes time  $O(\log n)$  due to the `CHANGEKEY` operation. So overall, the inner **for** loop contributes  $O(m \log n)$  time. □

# Greedy Algorithms

- A *greedy algorithm* builds the solution step by step, making a locally optimal choice at each step.
- In other words, a greedy algorithm does not look ahead.
- Prim's algorithm is a greedy algorithm: At each step, it extends the MST by adding the shortest available edge.
- In the case of MSTs, we obtain a globally optimal solution thanks to the lemma on Slide 10.
- Unfortunately, for most problems, greedy algorithms do not return a globally optimal solution.
- In practice, they are often used to obtain approximate solutions.

# Kruskal's algorithm

- Another greedy algorithm for MST is *Kruskal's algorithm*.
- It considers the edges one by one, by increasing weight. The current edge is inserted into the solution as long as it does not create a cycle.

## Pseudocode

```
1: procedure KRUSKAL( $G(V, E)$ )
2:   Sort  $E$  into  $e_1, e_2, \dots, e_m$  by increasing weight
3:    $F \leftarrow$  empty list of edges
4:   for  $i \leftarrow 1, m$  do
5:     if  $F \cup \{e_i\}$  contains no cycle then
6:        $F \leftarrow F \cup \{e_i\}$ 
7:   return  $T = (V, F)$ 
```

# Kruskal's algorithm

- There is also an efficient implementation of Kruskal's algorithm that runs in  $O(m \log n)$  time.
- It is described in the textbook. (Section 23.2)
- We will not cover it in CSE331. The difficulty is to detect cycles efficiently. (Line 5.)